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LAUNCHER, GRENADE, XM129: ANALYSIS OF STRESSES DUE TO DYNAMIC LOADS

Technical Report

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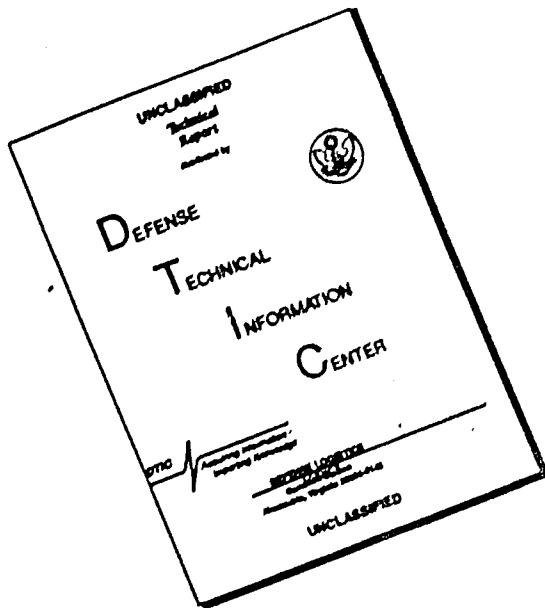
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LAUNCHER, GRENADE, XM129: ANALYSIS OF STRESSES DUE TO DYNAMIC LOADS

Technical Report

McInnis, W. T.

PROJECT TITLE: Aircraft Suppressive Fire Systems

PRON: EJ-2-50007-01-M1-M6

Preparing Agency: Springfield Armory, Springfield, Massachusetts

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ABSTRACT

An analysis of the XM129 grenade launcher was conducted to determine the dynamic loads, the resultant stresses, and the operational power requirements. General relationships defining the loads were derived. The equations were evaluated at various points. Power requirements and stresses were determined based upon these equations. The results can be used to facilitate the analysis of any future design changes.

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SUBJECT

A theoretical analysis was made of the XM129 grenade launcher.

OBJECTIVES

1. To determine the load and the stress levels of the various functional components of the weapon under normal firing conditions.
2. To ascertain the operational power requirements.
3. To provide general relationships which would facilitate analysis of the effects of any future design changes.

SUMMARY OF CONCLUSIONS

1. A firing rate of 300 rounds per minute is obtainable with the use of a 3/4 horsepower motor.
2. The stress levels of the critical components are well within the allowable limits.

RECOMMENDATION

A roller device should be incorporated in the follower stud design to reduce friction between the stud and the stud guide.

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1. INTRODUCTION

The XM129 is an automatic, 40mm, grenade launcher powered by an electric motor. The weapon has a fixed breech and a reciprocating barrel. The operation is controlled by three cams: the barrel cam, the locking cam, and the feed cam. Chambering is accomplished as the barrel is driven rearward over the round by an internal drum type cam; this action incloses the cartridge and disconnects the link from the adjacent round in the belt. At the same time, the barrel cocks the firing mechanism. When the barrel reaches the rearward position, the locking cam provides translational motion to a sliding barrel lock which engages a recess provided in the barrel. After the firing and dwell portions of the cycle have been completed, the barrel is unlocked and driven forward. The feed cam then functions the feed system, which is a gear and lever arrangement driving a feed slide. The weapon cycle is then completed.

2. PROCEDURE

a. A dynamic force analysis was conducted to determine the stresses and the power requirements. General equations, defining the theoretical loads on the critical components, were derived. The equations were then evaluated and the results tabulated (Appendix A).

b. The results of the force analysis's were used to calculate the power requirements (Appendix B).

c. The calculated maximum stresses for the critical components based on the theoretical force analysis are given in Appendix C.

3. CONDITIONS OF ANALYSIS

Analysis of the XM129 was based upon the assumptions that:

- a. the rate of fire of the weapon is 300 rounds per minute,
- b. total weight of the ammunition belt is 60 pounds,
- c. belt pull is constant,
- d. coefficients of friction are values believed reasonable with normal surface finishes and lubrication conditions,
- e. masses of relatively light components can be ignored,
- f. bodies under load are in a biaxial state of stress,
- g. frictional forces of small magnitude can be neglected.

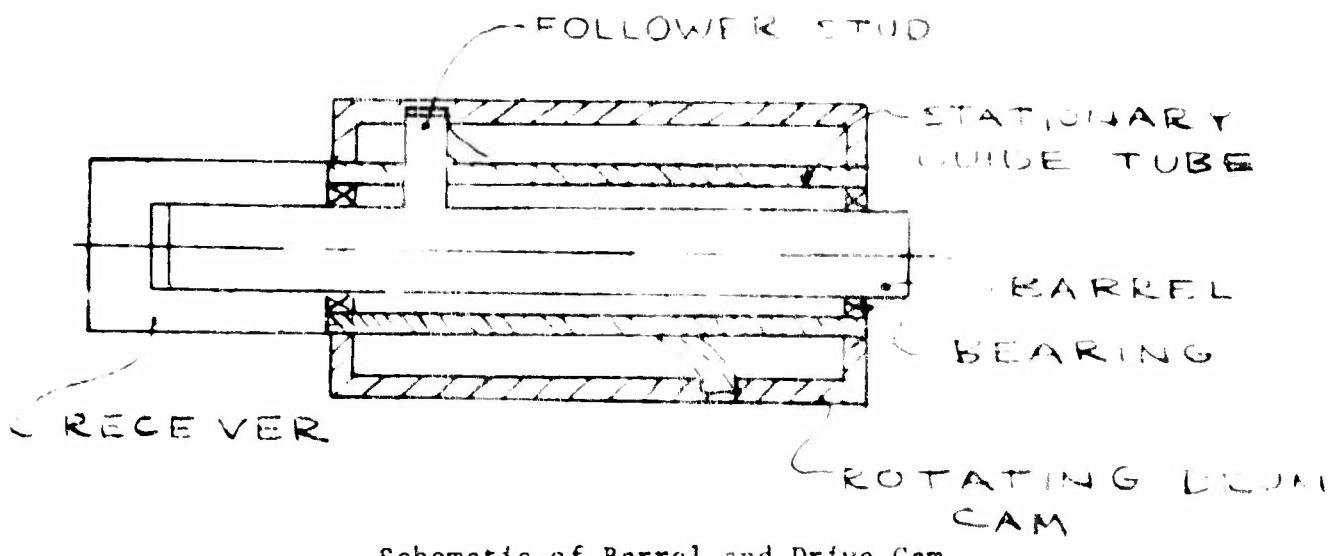
4. SYMBOLS

p Pressure  
P<sub>g</sub> Gear diametral pitch  
P<sub>f</sub> Cam driving force  
P<sub>a</sub> Ammunition belt pitch  
P<sub>c</sub> Horizontal force on feed lever  
P<sub>t</sub> Feed gear contact force  
P<sub>d</sub> Force on cam follower  
P<sub>l</sub> Total ammunition belt load  
P<sub>b</sub> Ammunition belt inertia load  
F<sub>l</sub>... Force  
Q Link stripping force  
T Torque  
R<sub>l</sub>... Reaction forces  
W Weight  
W<sub>1</sub> Dynamic tooth load  
W<sub>a</sub> Ammunition belt weight per linear inch  
W<sub>b</sub> Total ammunition belt weight  
V<sub>f</sub> Feed velocity  
K Link extension rate  
I Moment of inertia  
M Moment  
Y Gear tooth form factor  
X Displacement  
dot{X} Velocity

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**4. SYMBOLS - Continued**

|                               |                          |
|-------------------------------|--------------------------|
| $\ddot{x}$                    | Acceleration             |
| $m$                           | Mass                     |
| $\theta$                      | Angular displacement     |
| $\omega$                      | Angular velocity         |
| $\alpha$                      | Angular acceleration     |
| $\Theta, \Phi, \beta, \alpha$ | Angles                   |
| $\mu, \alpha$                 | Coefficients of friction |
| a, b, ....                    | Dimensional constants    |



Schematic of Barrel and Drive Cam

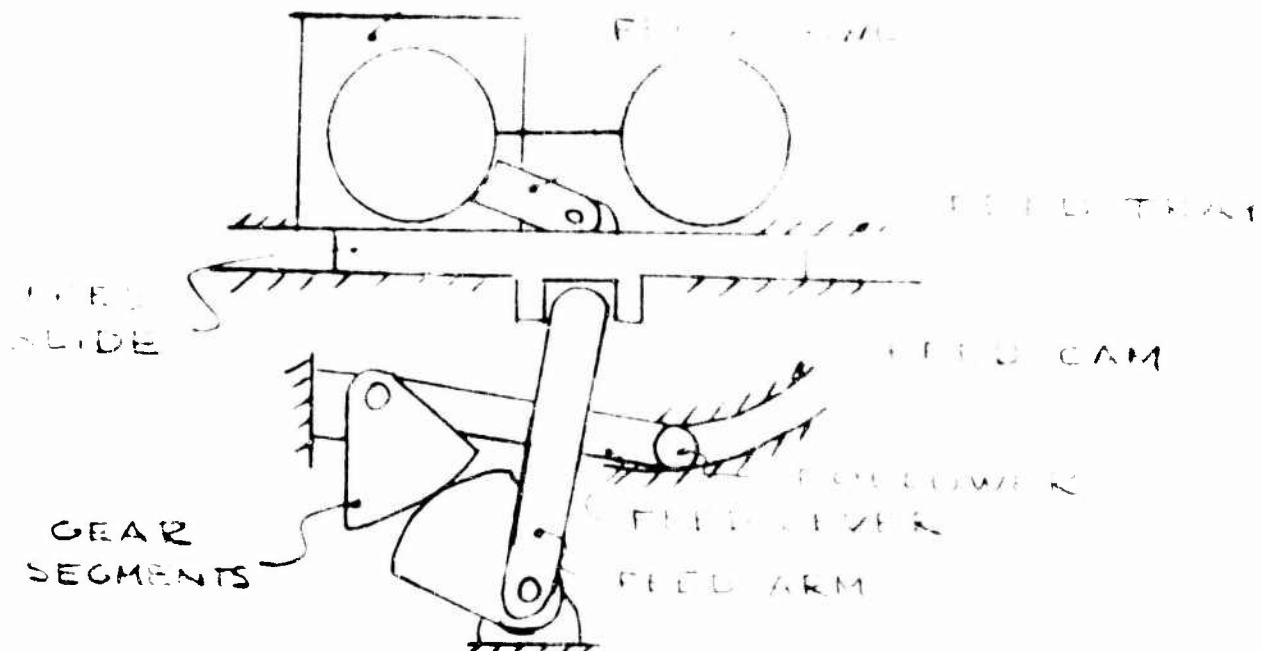
## 5. BARREL AND DRIVE CAM ANALYSIS

The barrel assembly consists primarily of the barrel and a follower stud, which is fastened to the top. The barrel is guided by a bearing at the front and by the receiver at the rear. The reactions at the points are shown on the barrel free body diagrams (Sheet 2, Appendix A) as  $R_1$ ,  $R_2$ ,  $F_1$ , and  $F_2$ . Rotational motion is prevented by the follower stud which is guided by a longitudinal slot in a tube encircling the barrel. The reaction at this point is designated by  $T_1$ .

In the cam development (Sheet 1 Appendix A),  $X$  is the longitudinal displacement,  $R$  is the cam radius, and  $\theta$  is angular displacement. From the development, it can be seen that the barrel is accelerated or decelerated in four areas. In these areas, the displacement equation is parabolic, which results in constant acceleration (Sheet 1, Appendix A). This means that, at any particular speed, the only variables in the analysis result from the geometric configuration. Maximum forces were determined by use of dynamic equilibrium equations derived at the eight points indicated on the cam layout, at the beginning and end of each parabolic segment. The equations were evaluated at these points with the use of the dimensions obtained from drawings and layouts. The results are tabulated on Sheet 6, Appendix A.

In the preliminary calculations, an assumed coefficient of sliding friction of 0.2 was used. This resulted in longitudinal friction forces higher than the driving force; in which case, the mechanism would be self-locking. A coefficient of 0.15, however, would give satisfactory results. In the field, the presence of dirt, wear, etc., could cause the coefficient to reach the 0.2 value, resulting in stalling. Since the major portion of the friction occurs at the interface between the follower stud and the guide tube, a roller device should be incorporated at this point to insure that the friction remains low.

RECEIVER



Schematic of Feed System

#### 6. FEED SYSTEM ANALYSIS

The feed cam is a face cam secured to the rear surface of the cam drum. The cam imparts motion to a follower which rotates the feed lever. The rotary motion is transferred through gear segments to the feed arm which in turn drives the feed slide. The feed slide is guided in the feed tray and, by means of a pawl, feeds the ammunition belt.

The belt load was calculated based on a constant feed velocity (Sheets 10, 11, 12; Appendix A). An expression was derived (Sheet 13, Appendix A) by equating the input and output torque<sup>s</sup> in terms of the cam contact force. By use of this equation, the point at which the maximum cam force occurred was determined. Free body diagrams were then drawn for the individual components, and equations relating the forces were derived. The dimensions corresponding to the point of maximum cam contact force were substituted, and the forces on each component calculated (Sheets 14 through 17, Appendix A).

#### 7. POWER ANALYSIS

The power required to operate the gun at a constant velocity is composed of two components: the power required to drive the barrel and the power required to function the feed system.

The power is the product of the average torque and the angular velocity.

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7. POWER ANALYSIS - Continued

The torque curves are plotted on Sheets 2 and 3, Appendix B. The average torque is the area under the curve divided by 360 degrees. By use of the average torque, the power requirement was calculated (Sheet 4, Appendix B). The operating power is 0.70 HP.

The power required to accelerate the gun to operating speed in 1.25 revolutions can be approximated (Sheet 5, Appendix B). The moment of inertia of the rotating parts was calculated and the accelerating horsepower was calculated (Sheet 6, Appendix B). The accelerating power requirement is 0.49 HP.

8. STRESS ANALYSIS

a. The maximum forces (Appendix A) were used to calculate the stresses on the feed system components (Sheet 1-7, Appendix C). The maximum stress developed, which is less than 60,000 psi, is within the allowable limits.

b. The forces determined (Appendix A) were used to calculate the stresses on the barrel lock and on the barrel cam follower (Sheets 8 and 9, Appendix C). The stresses here are only 5000 psi (shear) in the lock and 4,400 psi in the follower.

c. The stresses in most of the components are of low magnitude. This indicates that the use of either low strength steels to decrease cost or lightweight alloys to reduce weight is possible.

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**APPENDICES**

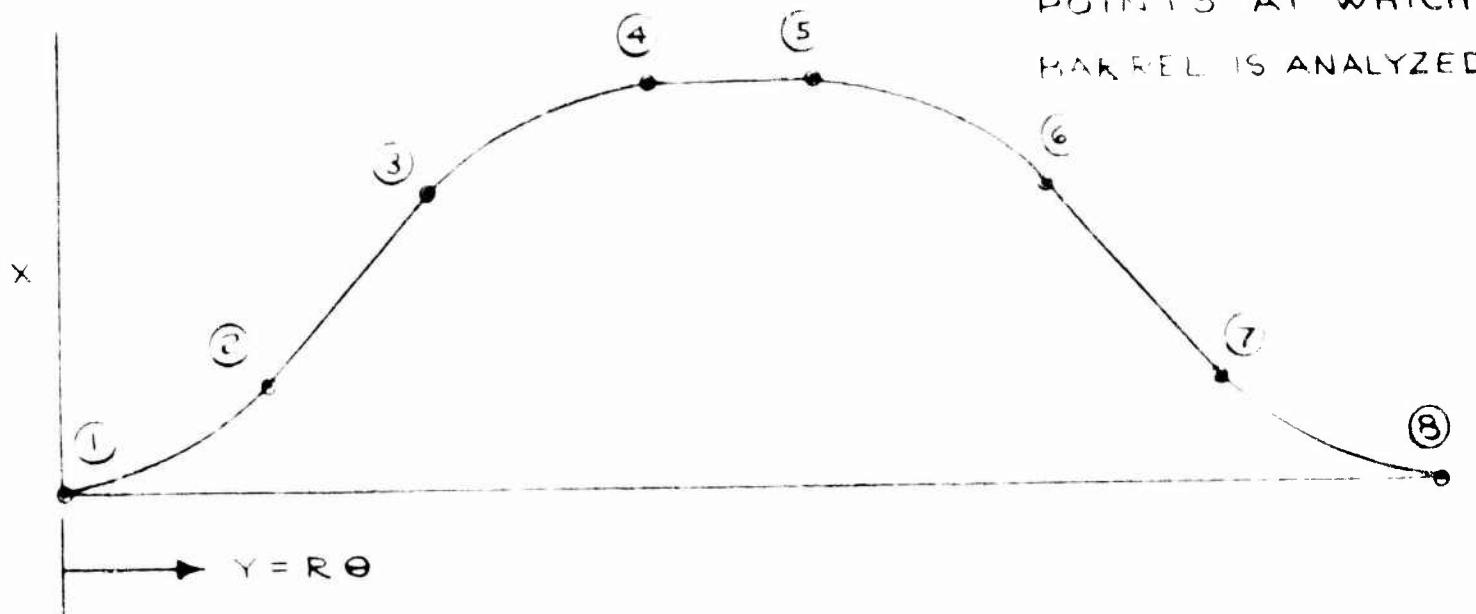
- A - Barrel Force Analysis**
- B - Feed System Force Analysis**
- C - Stress Analysis**
- D - Distribution**

**APPENDIX A**

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**Barrel Force Analysis**

## BARREL FORCE ANALYSIS

DEVELOPMENT OF CAM

$$x = Ky^2 \quad \text{FOR PARABOLIC SEGMENTS OF CAM}$$

$$y = R\theta$$

$$x = KR^2\theta^2$$

$$\theta = \omega t$$

$$x = KR^2\omega^2 t^2$$

$$\dot{x} = \frac{dx}{dt} = 2KR^2\omega^2 t$$

$$\ddot{x} = \frac{d^2x}{dt^2} = 2KR^2\omega^2$$

FROM DWG. SA-F 42774

$$K = .216$$

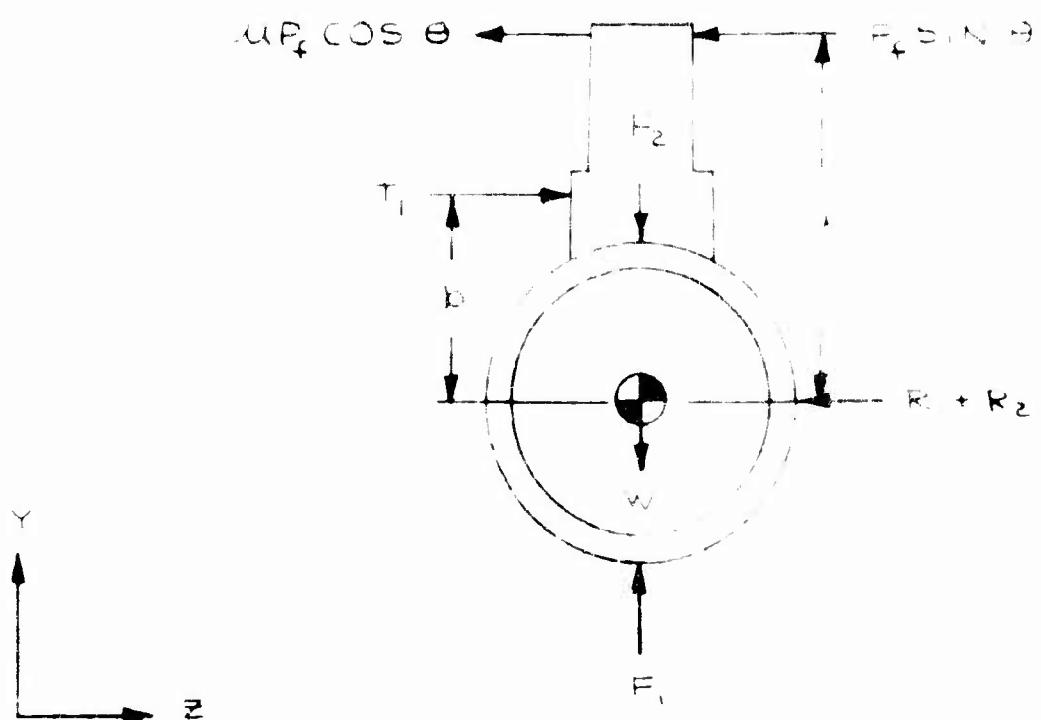
$$R = 2.6$$

$$\omega = 31.4 \text{ RAD./SEC.}$$

SUBSTITUTING IN ABOVE EQUATIONS

$$\dot{x} = 2866 \text{ IN/SEC.}^2$$

BARREL FORCE ANALYSIS - Continued



**BARREL FORCE ANALYSIS - Continued**

$$\sum \text{M}_{G(YZ)} = 0$$

$$bT_1 - \alpha \mu R_* \cos \theta - \alpha R_* \sin \theta$$

$$T_1 = \frac{\alpha}{b} (R_* \sin \theta + \mu R_* \cos \theta) \quad \underline{\text{EQ. 1}}$$

$$\sum F_{(YZ)} = 0$$

$$T_1 - \mu R_* \cos \theta - R_* \sin \theta - (R_1 + R_2) = 0$$

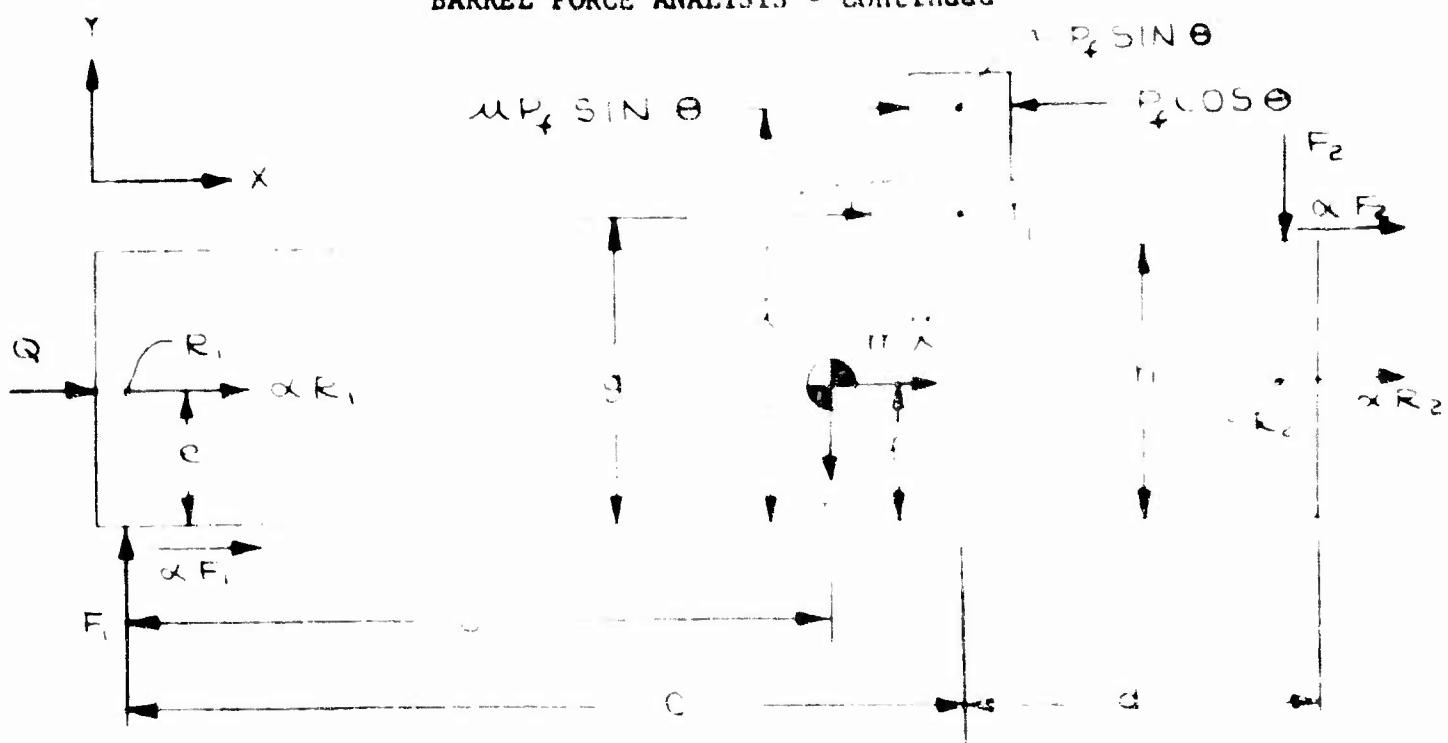
$$R_1 + R_2 = \frac{\alpha}{b} (R_* \sin \theta + \mu R_* \cos \theta) - R_* \sin \theta - \mu R_* \cos \theta$$

$$R_1 + R_2 = \left(\frac{\alpha}{b} - 1\right)(R_* \sin \theta + \mu R_* \cos \theta) \quad \underline{\text{EQ. 2}}$$

$$R_1 = \frac{\alpha + \alpha h/2}{S+d} \left(\frac{\alpha}{b} - 1\right)(R_* \sin \theta + \mu R_* \cos \theta) \quad \underline{\text{EQ. 3}}$$

$$R_2 = \frac{S - \alpha h/2}{S+d} \left(\frac{\alpha}{b} - 1\right)(R_* \sin \theta + \mu R_* \cos \theta) \quad \underline{\text{EQ. 4}}$$

BARREL FORCE ANALYSIS - Continued



SIDE VIEW OF BARREL  
AT POSITIONS (1 2 3 4)

$$\sum F_{(YX)} = 0$$

$$F_1 = F_2 + W$$

EQ. 5

$$\sum M_{F_1}(X, Y) = 0$$

$$F_2 = \frac{\lambda P \cos \theta + \mu P \sin \theta - \alpha T_1 - \alpha k_2 x - WJ + m \ddot{x} CQ}{c + d + \alpha + h} \quad \text{EQ. 6}$$

$$\sum F_x(XY) = 0$$

$$Q + \alpha(R_1 + R_2) + \alpha(2F_2 + W) + m\ddot{x} + \alpha T_1 + \mu P \sin \theta - P \cos \theta = 0 \quad \text{EQ. 7}$$

BARREL FORCE ANALYSIS - Continued

IF THE SAME ANALYSIS IS USED AT POINTS

(5) (6) (7) (8) THE FOLLOWING EQUATIONS RESULT

POSITIONS (5) & (6)

$$T_1 = \frac{\alpha}{b} (P_f \sin \theta + \mu P_f \cos \theta)$$

EQ. 8

$$R_1 + R_2 = \left(\frac{\lambda}{b} - 1\right) (P_f \sin \theta + \mu P_f \cos \theta)$$

EQ. 9

$$R_1 = \frac{d - \alpha h/2}{c + d} \left(\frac{\lambda}{b} - 1\right) (P_f \sin \theta + \mu P_f \cos \theta)$$

EQ. 10

$$R_2 = \frac{s + \alpha h/2 - (\lambda/b - 1)}{c + d} (P_f \sin \theta + \mu P_f \cos \theta)$$

EQ. 11

$$F_1 = \frac{-P_f \cos \theta - i \mu P_f \sin \theta - \alpha T_1 g - \alpha (R_1 + R_2) \dot{x} + fm \ddot{x} - dw}{c + d + \alpha h}$$

EQ. 12

$$P_f \cos \theta - \mu P_f \sin \theta + m \ddot{x} - \alpha T_1 - \alpha (R_1 + R_2) - \alpha (2 F_1 + w) = 0$$

EQ. 13

POSITIONS (7) & (8)

$$T_1 = \frac{\alpha}{b} (P_f \sin \theta - \mu P_f \cos \theta)$$

EQ. 14

$$R_1 + R_2 = \left(\frac{\lambda}{b} - 1\right) (P_f \sin \theta - \mu P_f \cos \theta)$$

EQ. 15

$$R_1 = \frac{d - \alpha h/2}{c + d} \left(\frac{\lambda}{b} - 1\right) (P_f \sin \theta - \mu P_f \cos \theta)$$

EQ. 16

$$R_2 = \frac{s + \alpha h/2}{c + d} \left(\frac{\lambda}{b} - 1\right) (P_f \sin \theta - \mu P_f \cos \theta)$$

EQ. 17

$$F_2 = \frac{\alpha (R_1 + R_2) \dot{x} + i \mu P_f \sin \theta + \lambda P_f \cos \theta + m \ddot{x} - w \dot{x} + \alpha T_1 g}{c + d + \alpha h}$$

EQ. 18

$$m \ddot{x} - \mu P_f \sin \theta - P_f \cos \theta - \alpha T_1 - \alpha (2 F_2 + w) - \alpha (R_1 + R_2) = 0$$

EQ. 19

BARREL FORCE ANALYSIS - Continued

VALUES FOR EQUATIONS

$$\begin{array}{lll}
 \alpha = 2.70 & g = 2.20 & k = 4.00 \\
 b = 1.00 & h = 1.87 & \alpha = 1.00 \\
 c = .935 & i = 2.44 & \lambda = 0.10 \\
 f = 0.94 & j = 4.00 & Q = 30.0
 \end{array}$$

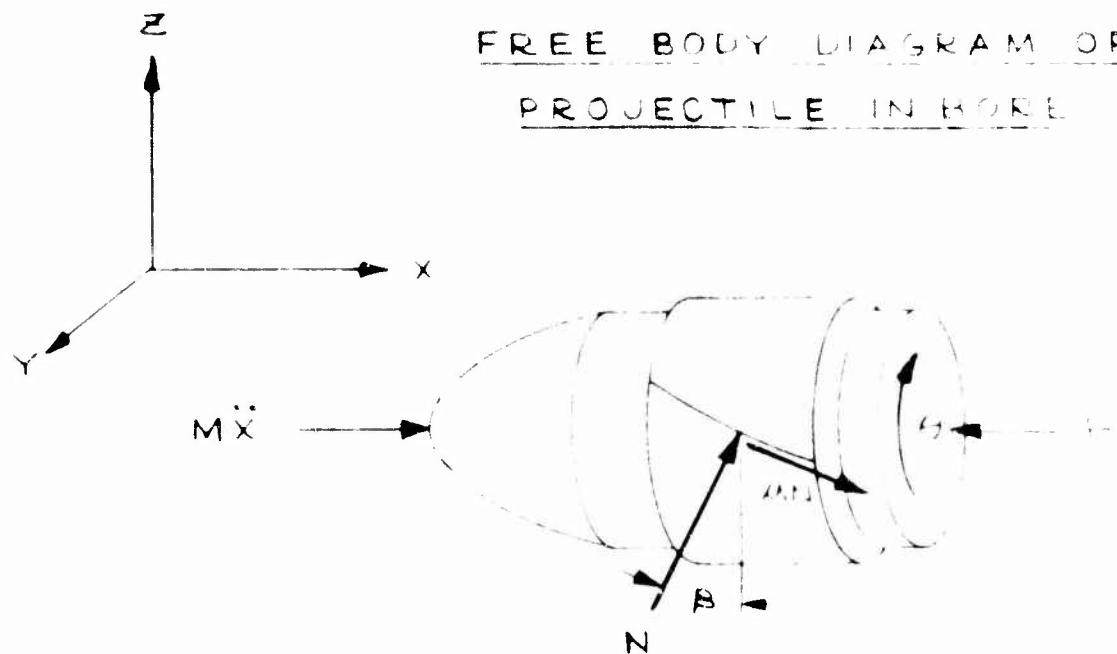
| POS      | 1         | 2          | 3          | 4         | 5         | 6          | 7          | 8         |
|----------|-----------|------------|------------|-----------|-----------|------------|------------|-----------|
| $\Theta$ | $0^\circ$ | $45^\circ$ | $45^\circ$ | $0^\circ$ | $0^\circ$ | $45^\circ$ | $45^\circ$ | $0^\circ$ |
| C        | 4"        | 4"         | 4"         | 4"        | 4"        | 4"         | 4"         | 4"        |
| d        | 1.5"      | 2.5"       | 5"         | 6"        | 4"        | 5"         | 2.5"       | 1.5"      |
| S        | 6.5"      | 5.5"       | 3'         | 2"        | 2"        | 2"         | 5.5"       | 4.5"      |
| Q        | 0         | 0          | 30*        | 30*       | 0         | 0          | 0          | 0         |
| X        | 2866      | 2866       | -2866      | -2866     | 2866      | -2866      | 2866       | 2866      |

TABLE I

SOLVING EQUATIONS ① THROUGH ③ FOR P YIELDS

| POS | 1    | 2     | 3    | 4   | 5    | 6    | 7     | 8     |
|-----|------|-------|------|-----|------|------|-------|-------|
| P   | 25.1 | 100.1 | 34.1 | 9.0 | 25.1 | 93.0 | -19.0 | -19.2 |

BARREL FORCE ANALYSIS - Continued



$N$ =LAND NORMAL FORCE

$M$ =PROJECTILE MASS

$\mu$ =COEFFICIENT OF FRICTION

$\ddot{x}$ =AXIAL ACCELERATION

$\ddot{\theta}$ =ANGULAR ACCELERATION

$\beta$ =LAND ANGLE

$I$ =PROJECTILE MOMENT OF INERTIA

$R$ =PROJECTILE RADIUS

$y$ =TANGENTIAL DISPLACEMENT

$\theta$ =ANGULAR DISPLACEMENT

$x$ =AXIAL DISPLACEMENT

$$\sum F_x = 0$$

$$M\ddot{x} + N \sin \beta + \mu N \cos \beta - F_t = 0 \quad \text{EQ. 1.}$$

$$\sum M_x = 0$$

$$R N \cos \beta - R \mu N \sin \beta - I \ddot{\theta} \quad \text{EQ. 2.}$$

BARREL FORCE ANALYSIS - Continued

$$Y = \tan B X$$

$$R\dot{\theta} = \tan B X$$

$$R\ddot{\theta} = \tan B \dot{X}$$

$$R\ddot{\theta} = \tan B \ddot{X}$$

$$\ddot{X} = \frac{R\ddot{\theta}}{\tan B}$$

FIG. 3

COMBINING EQUATIONS ① & ③

$$\ddot{\theta} = (F - N \sin B - \mu N \cos B) \frac{\tan B}{RM}$$

COMBINING WITH EQUATION ②

$$R(N \cos B - \mu N \sin B) - \frac{I}{RM} \tan B (F - N \sin B - \mu N \cos B) = 0$$

$$M = .00097$$

$$\mu = .3$$

$$I = .0003$$

$$F = PA = 17,350$$

$$R = .785$$

$$\theta = 6^\circ$$

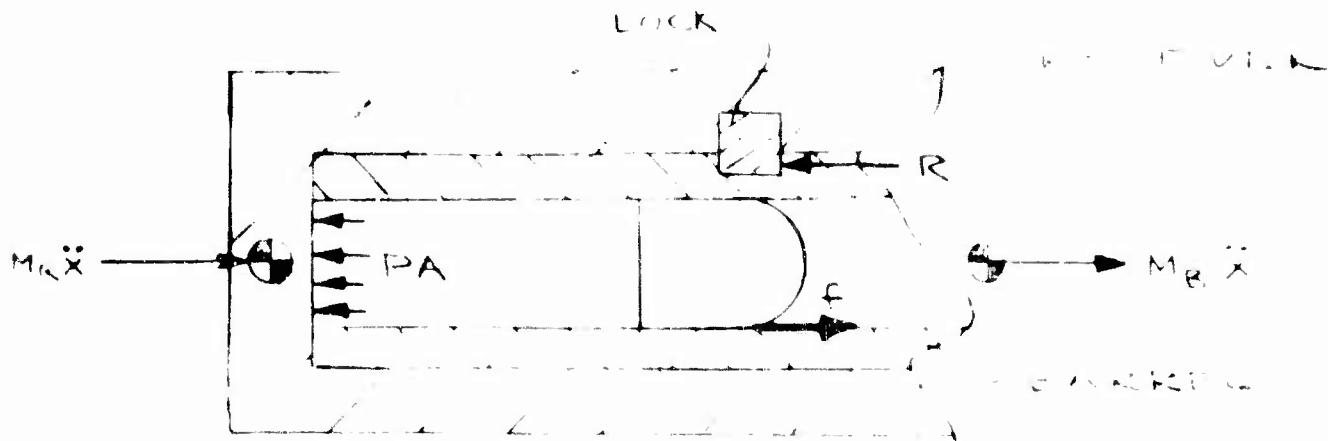
SOLVING FOR N

$$N = 910 \#$$

$$\text{TORQUE} = (N \cos B - \mu N \sin B) R$$

$$\text{TORQUE} = 705 \# \text{ IN.}$$

BARREL FORCE ANALYSIS - Continued



$M_R$  = MASS OF GUN - MASS OF BARREL

$M_B$  = MASS OF BARREL

$PA$  = GAS PRESSURE FORCE

$f$  = TANGENTIAL RIFLING REACTION

$R$  = FORCE ON LOCK

EQUILIBRIUM EQUATION OF ENTIRE GUN

$$\ddot{x} = \frac{PA + f}{M_R + M_B} \quad \text{EQ.1}$$

EQUILIBRIUM EQUATION OF BARREL

$$R = f + M_B \ddot{x} \quad \text{EQ.2}$$

EQ.1 + 2

$$R = \frac{M_B}{M_R + M_B} (PA) + f \left( 1 - \frac{M_B}{M_R + M_B} \right) \quad \text{EQ.3}$$

$$R = \frac{2.5}{42} (19,000) + 2.32 \left( 1 - \frac{2.5}{42} \right)$$

$$R = 1350 \#$$

SHEET 9 of 17

BARREL FORCE ANALYSIS - Continued

CALCULATION OF BELT LOAD

$$P_t = P_b + \alpha W_b$$

EQ. A

$$P_b = \frac{V_f}{19.65} \left( \frac{P_w}{K} \right)^2$$

EQ. B

WHERE:

$P_t$  = TOTAL BELT LOAD

$P_b$  = BELT INERTIA LOAD

$W_b$  = TOTAL BELT WEIGHT

$V_f$  = FEED VELOCITY

$P_a$  = PITCH

$w$  = BELT WEIGHT PER LINEAR INCH

$K$  = LINK EXTENSION RATE

$$V_f = \frac{\omega P 360^\circ}{\Delta \theta}$$

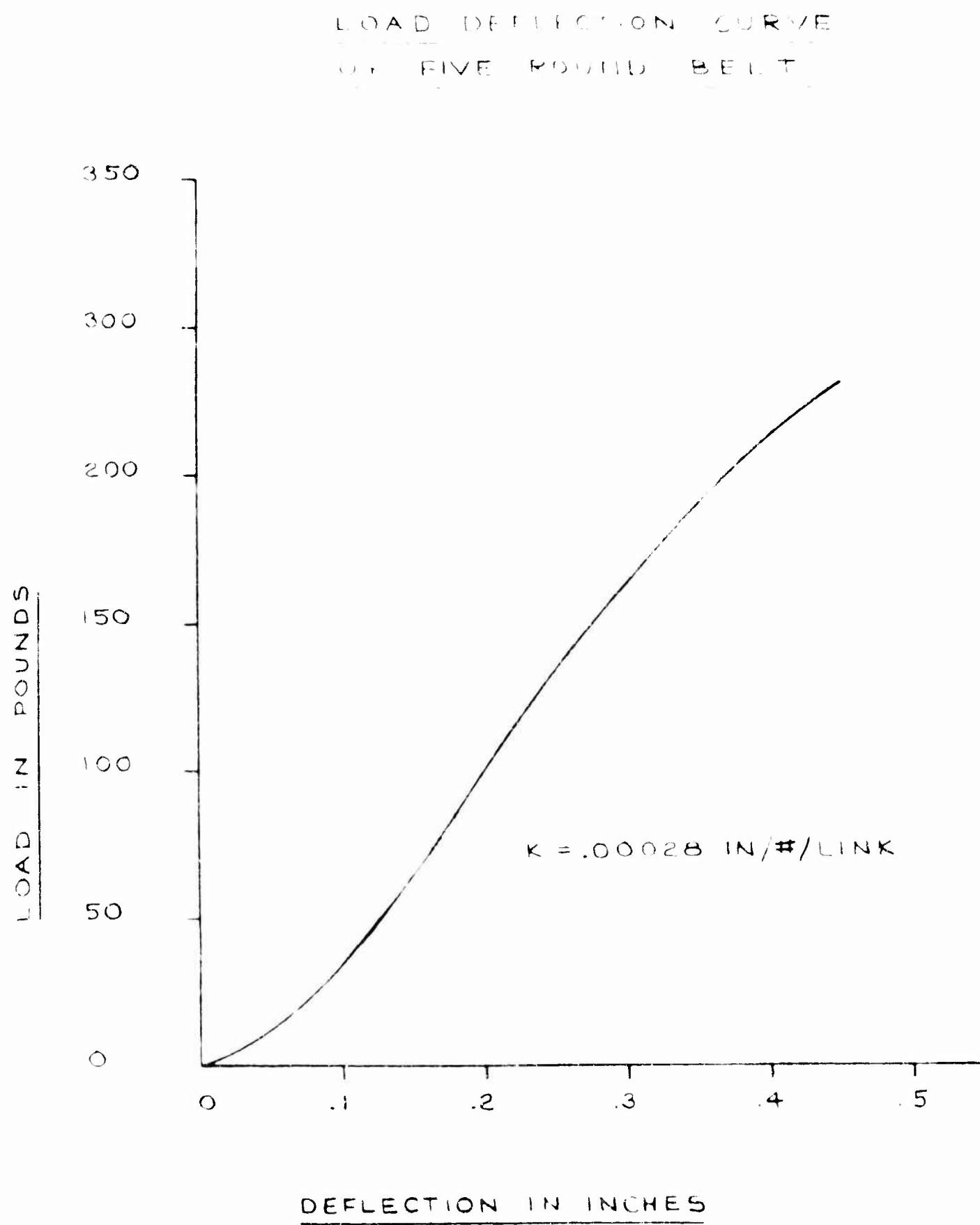
EQ. C

WHERE:

$\omega$  = ANGULAR VELOCITY

$\Delta \theta$  = ANGULAR DISPLACEMENT DURING FEEDING

BARREL FORCE ANALYSIS - Continued



## BARREL FORCE ANALYSIS - Continued

$$K = .00028 \text{ IN/ft/LINK}$$

$$w = .342 \text{ #/IN}$$

$$P_g = 1.9 \text{ IN}$$

$$\omega = 5 \text{ REV/SEC}$$

$$\Delta\theta = 44^\circ$$

FROM EQUATION C

$$V_F = 77 \text{ IN/SEC}$$

FROM EQUATION B

$$P_b = \frac{77}{19.65} \left( \frac{1.9 \times .342}{.00028} \right)^{\frac{1}{2}}$$

$$\alpha \approx .15$$

$$w_b \approx 60 \text{ #}$$

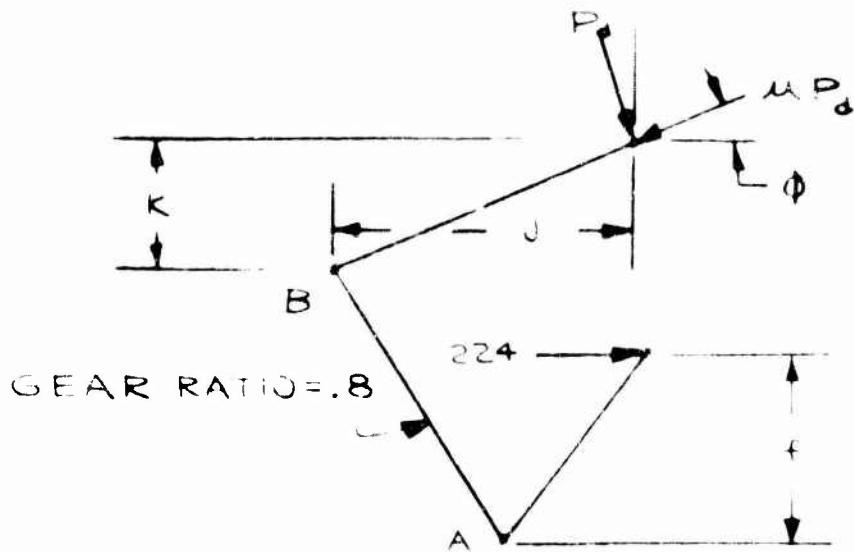
FROM EQUATION A

$$P_L = 200 \text{ #}$$

$$P = P_L / \cos \theta$$

$$P = 230 \text{ #}$$

BARREL FORCE ANALYSIS - Continued



FREE BODY DIAGRAM OF FEED ASSEMBLY

$$.8) \sum M_A = \sum M_B$$

$$.8) 224 f = P_d J (\cos \phi + \mu \sin \phi) + P_d K (\sin \phi - \mu \cos \phi) \quad \underline{\text{EQ. D}}$$

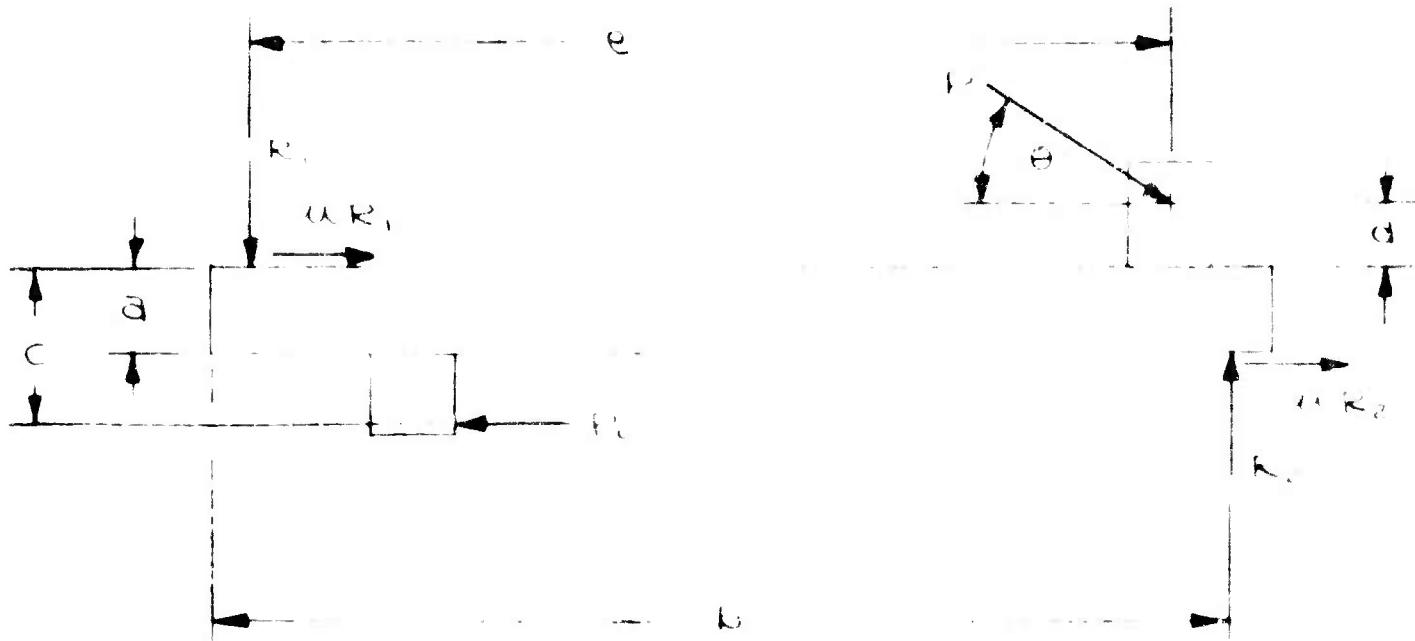
EQUATION D IS SOLVED AT 5 POINTS

FROM LAYOUT

| POS    | ①         | ②          | ③          | ④          | ⑤         |
|--------|-----------|------------|------------|------------|-----------|
| $\mu$  | .08       | .08        | .08        | .08        | .08       |
| $\phi$ | $0^\circ$ | $38^\circ$ | $52^\circ$ | $50^\circ$ | $0^\circ$ |
| $f$    | 1.85      | 2.05       | 2.12       | 2.0        | 1.8       |
| $J$    | 1.10      | 1.20       | 1.22       | 1.19       | 1.07      |
| $K$    | .55       | .30        | 0          | -.28       | -.50      |
| $P$    | 313       | 313        | 460        | 580        | 290       |

TABLE 3

BARREL FORCE ANALYSIS - Continued



FREE BODY DIAGRAM OF FREE FALL BULLET

$$\sum F_x = 0$$

$$\mu R_1 + \mu R_2 + P \cos \theta + m \ddot{x} - P_c = 0$$

$$\sum F_y = 0$$

$$R_1 + P \sin \theta - R_2 = 0$$

$$\sum M_R_1$$

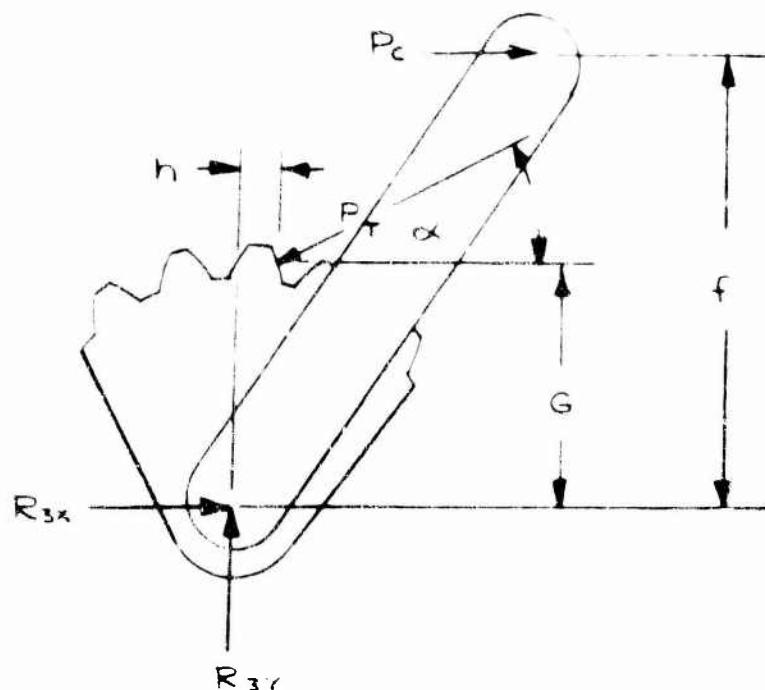
$$b R_2 + a \mu R_2 + a/2 m \ddot{x} - c P_c - e P \sin \theta - d P \cos \theta$$

COMBINING EQUATIONS (1) (2) & (3)

$$(P_c + \mu P \sin \theta - P \cos \theta - m \ddot{x}) \left( \frac{b}{2\mu} + \frac{a/2}{e/m} \right) + a/2 m \ddot{x} - c P_c$$

$$e P \sin \theta - d P \cos \theta = 0$$

BARREL FORCE ANALYSIS - Continued



FREE BODY DIAGRAM OF FEED LEVER

$$\sum F_x = 0$$

$$P_T \cos \alpha - R_{3x} - P_c = 0$$

EQ. 5

$$\sum F_y = 0$$

$$P_T \sin \alpha - R_{3y} = 0$$

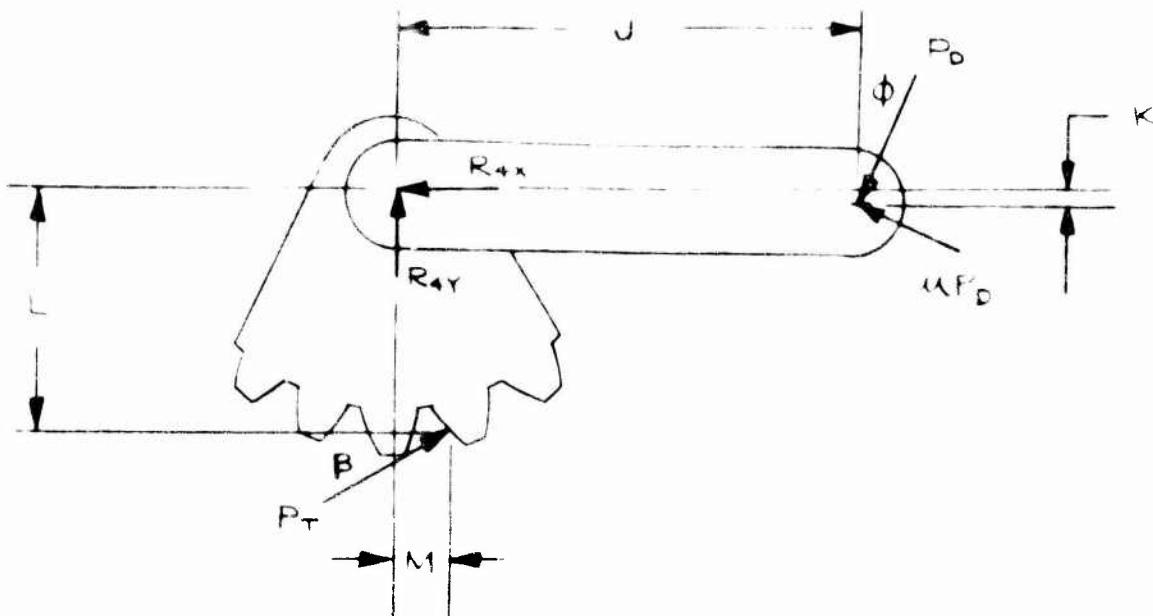
EQ. 6

$$\sum M_{R_3} = 0$$

$$f P_c + h P_T \sin \alpha - G P_T \cos \alpha = 0$$

EQ. 7

BARREL FORCE ANALYSIS - Continued



FREE BODY DIAGRAM OF CAM FOLLOWER AND GEAR

$$\sum F_x = 0$$

$$P_D \sin \phi + R_{4x} - P_T \cos \beta + \mu P_D \cos \phi = 0 \quad \underline{\text{EQ. 8}}$$

$$\sum F_y = 0$$

$$P_D \cos \phi - R_{4y} - P_T \sin \beta - \mu P_D \sin \phi = 0 \quad \underline{\text{EQ. 9}}$$

$$\sum M_{R4} = 0$$

$$L P_T \cos \beta + M P_T \sin \beta - K P_D \sin \phi - J P_D \cos \phi - \mu K P_D \cos \phi + \mu J P_D \sin \phi = 0 \quad \underline{\text{EQ. 10}}$$

FROM LAYOUT OF ASSEMBLY AT POINT ④

$a = .19$        $e = .8$        $u = 1.19$        $\theta = 50^\circ$        $\phi = 50$   
 $b = 4.2$        $t = 2.0$        $K = .8$        $\alpha = 5^\circ$   
 $c = .25$        $g = .7$        $l = .8$        $\beta = 5^\circ$   
 $d = .25$        $h = .5$        $M = .65$        $M = .08, .15$

FROM EQUATIONS 1 → 4

$$F_c = 22.4 \text{ #}$$

$$R_1 = 13.25 \text{ #}$$

$$R_2 = 128.2 \text{ #}$$

$$m\ddot{x} = 4.0 \text{ #}$$

$$\alpha R_1 = 1.98 \text{ #}$$

$$\alpha R_2 = 19.24 \text{ #}$$

FROM EQUATIONS 5 → 7

$$P_T = 553 \text{ #}$$

$$R_{3Y} = 453 \text{ #}$$

$$R_{3X} = 93 \text{ #}$$

FROM EQUATIONS 8 → 10

$$P_D = 575 \text{ #}$$

$$R_{4Y} = 695 \text{ #}$$

$$R_{4X} = -19 \text{ #}$$

**APPENDIX B**

**REPORT  
SA-TR20-2741**

**Power Analysis**

POWER ANALYSIS

TORQUE REQUIRED TO DRIVE BARREL

$$\text{TORQUE} = F R$$

WHERE:

F = CAM DRIVING FORCE (TANGENTIAL)

R = CAM RADIUS

VALUES FOR F WERE TAKEN FROM TABLE 2  
AND THE TORQUE CURVE PLOTTED ON SHEET  
AVERAGE TORQUE IS THE AREA UNDER THE  
CURVE DIVIDED BY  $360^\circ$

AVERAGE TORQUE = 70 IN. $\cdot$ #

TORQUE REQUIRED TO FEED

$$\text{TORQUE} = S R$$

WHERE:

S = CAM DRIVING FORCE (TANGENTIAL)

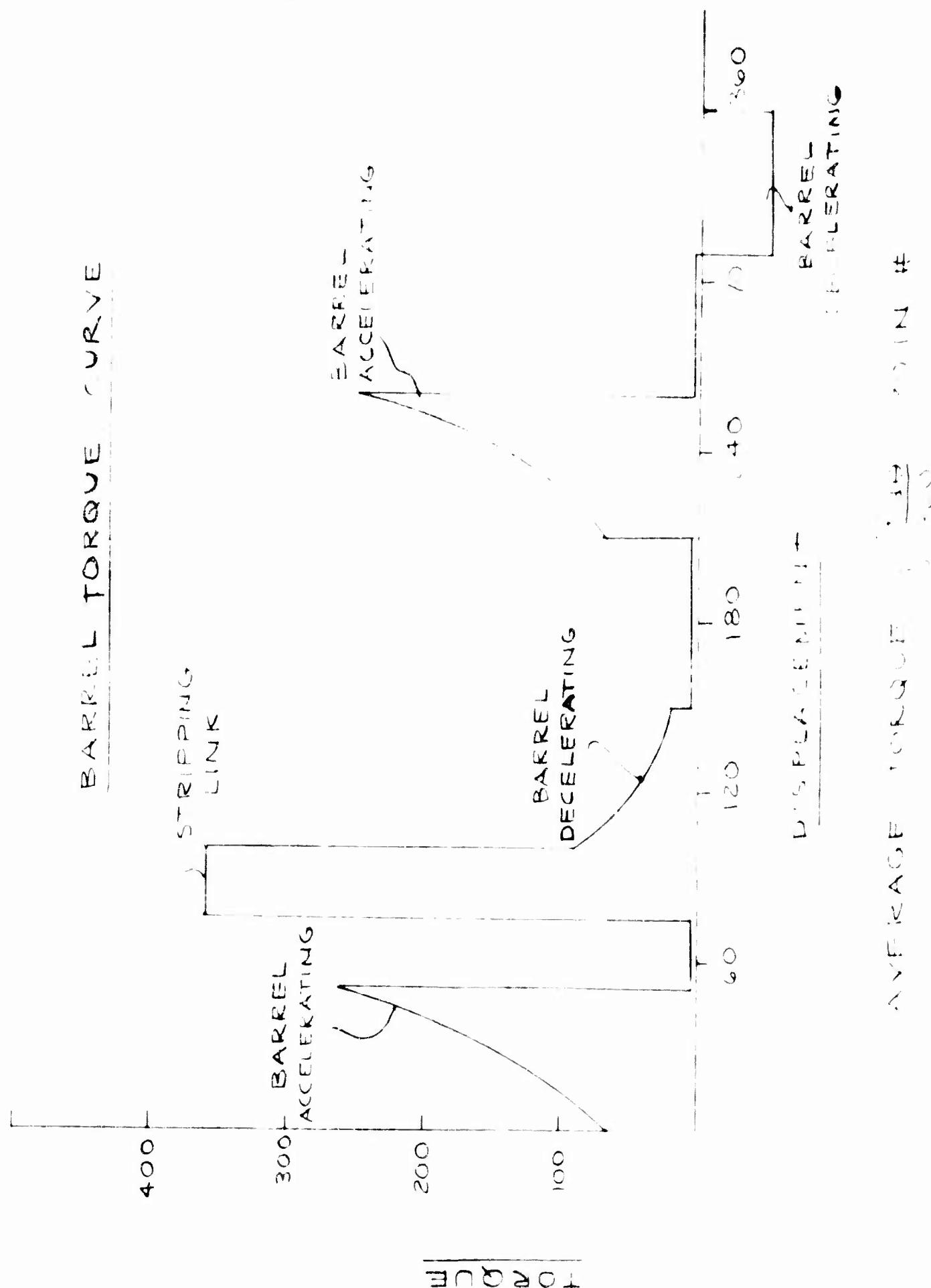
R = CAM RADIUS

VALUES FOR S WERE TAKEN FROM TABLE 3  
AND VALUES FOR R FROM DWG. SA-D-49291.  
TORQUE CURVE IS PLOTTED ON SHEET .

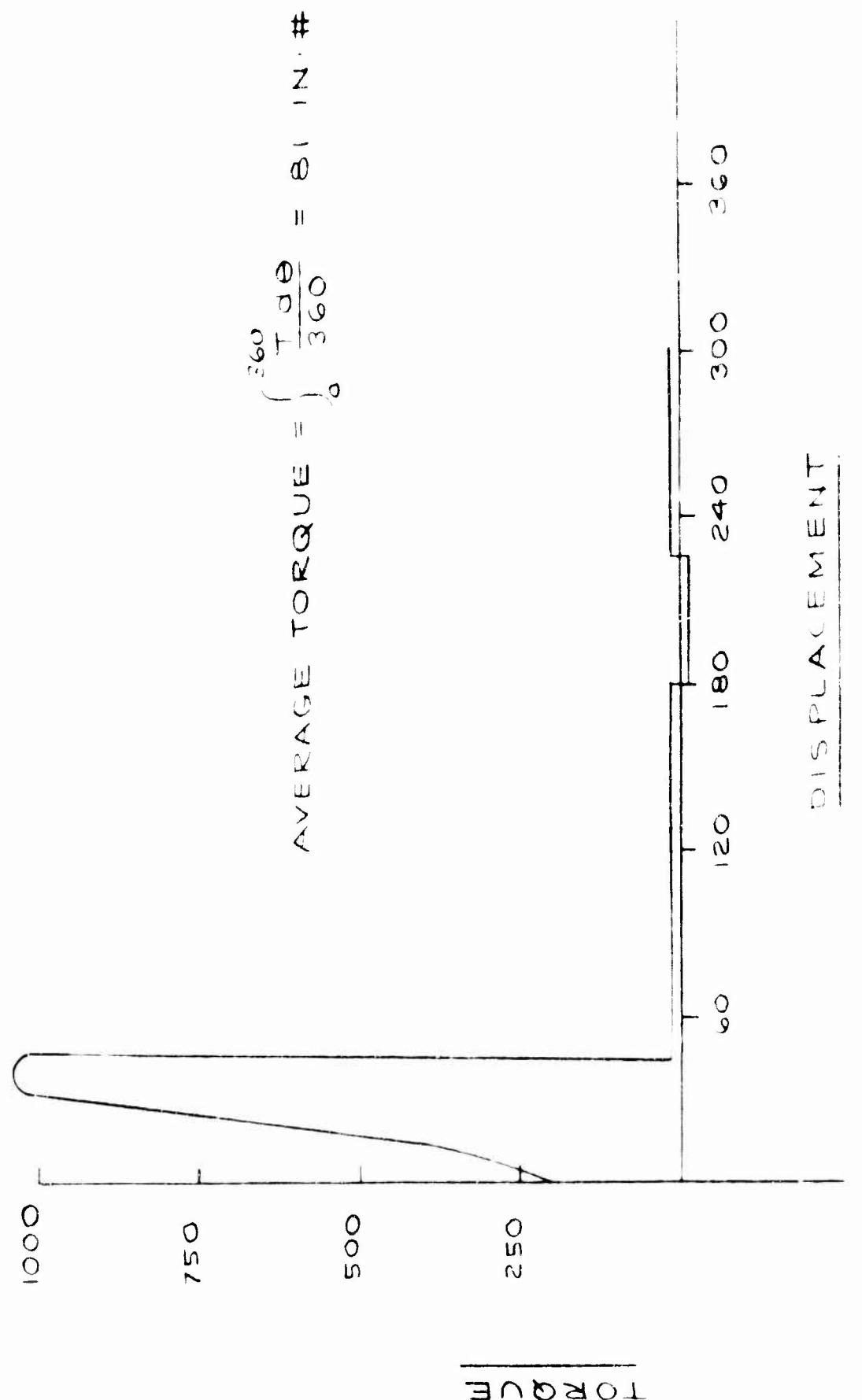
AVERAGE TORQUE = 81 IN. $\cdot$ #

TOTAL AVERAGE TORQUE  $T_{AV}$  = 151 IN. $\cdot$ #

POWER ANALYSIS



POWER ANALYSIS



POWER ANALYSIS

HORSEPOWER REQUIRED TO OPERATE GUN  
AT 300 R.P.M.

$$H.P. = \frac{T \times \omega \times 2\pi}{12 \times 550}$$

WHERE:

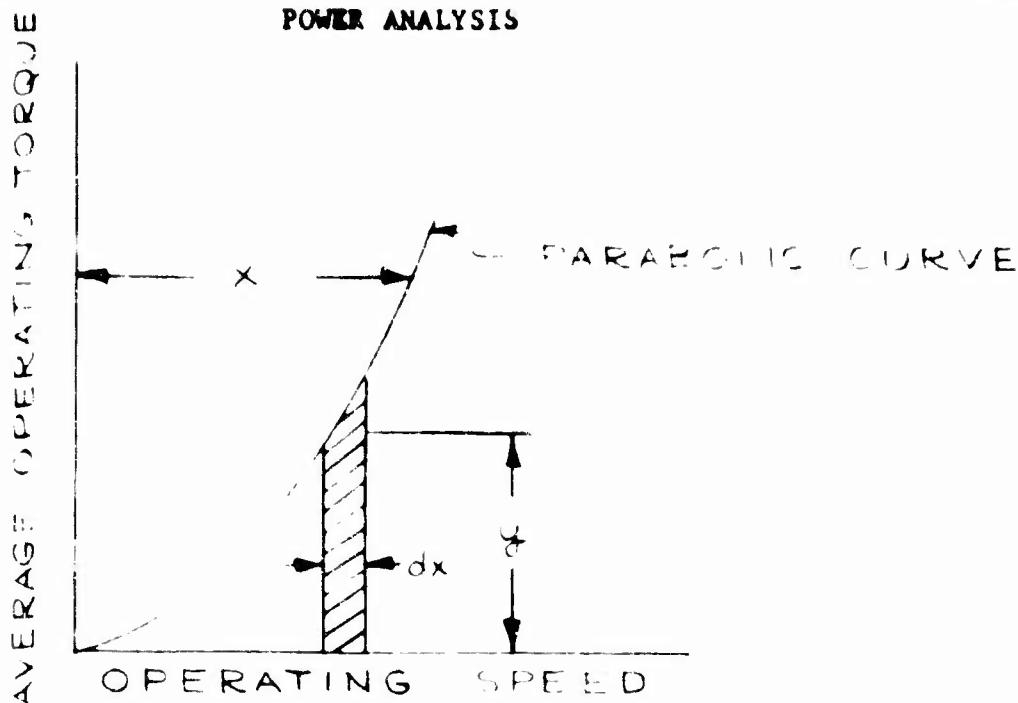
T = AVERAGE TORQUE IN IN. #

$\omega$  = ANGULAR VELOCITY IN REV/SEC

$$H.P. = \frac{151 \times 5 \times 2\pi}{12 \times 550}$$

$$H.P. = .70$$

POWER ANALYSIS



ACCELERATING TORQUE IS THE TORQUE TO ACCELERATE THE DRUM AND CAMS PLUS THE AVERAGE OPERATING TORQUE, FROM ZERO R.P.M. TO OPERATING SPEED.

$$\text{AVERAGE } T = \frac{\int_0^x y dx}{x}$$

$$y = kx^2$$

$$T_{av} = \frac{kx^3}{3}$$

$$\text{ACCELERATING TORQUE} = I\alpha + \frac{T_0}{3}$$

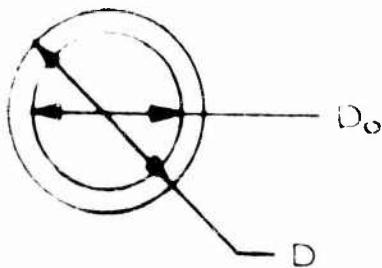
WHERE:

I = MOMENT OF INERTIA OF DRUM AND CAMS

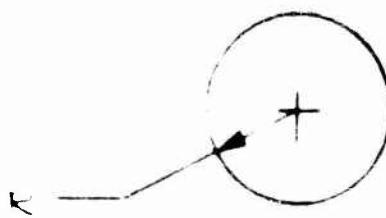
$\alpha$  = ANGULAR ACCELERATION

T = OPERATING TORQUE

POWER ANALYSIS



DRUM AND MAIN CAM



GEAR, FEED, AND LOCK CAMS

$$I_0 = m \pi l \left( \frac{D}{2} \right)^4 - \left( \frac{D_o}{2} \right)^4$$

$$I_0 \approx .205$$

$$I_G = \frac{M R^2}{2}$$

$$I_G \approx .36$$

$$I_T = I_0 + I_G$$

$$I_T = .565$$

$$T_a = T \alpha + \frac{T_0}{3}$$

$$\omega \text{ IS } 0^\circ/\text{SEC} \rightarrow 5^\circ/\text{SEC} = 25^\circ/\text{SEC} = 1.25 \text{ IN } .5 \text{ SEC}$$

$$T_a = .565 (62.8) + \frac{1.51}{3} (1.25)$$

$$T_a = 9.8 \text{ N} \cdot \# (\text{FOR 1.25 REV. OR .5 SEC})$$

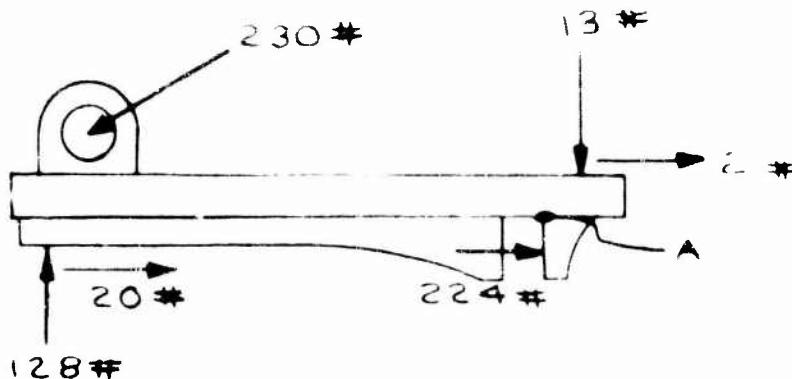
$$H.P. = .47$$

**REPORT**  
**SA-TR20-2741**

**APPENDIX C**

**STRESS ANALYSIS**

## STRESS ANALYSIS

FEED SLIDESHEAR IN PIN

$$S = \frac{P}{A}$$

$$S = \frac{230 \times 4}{2 \times .7854 \times .25^2}$$

$$S = 2400 \text{ P.S.I.}$$

BEARING IN HOLE

$$S = \frac{P}{A}$$

$$S = \frac{230}{.484 \times .25}$$

$$S = 1900 \text{ P.S.I.}$$

COMBINED BENDING AND COMPRESSION IN LUG

$$S = \frac{MC}{I} + \frac{P}{A}$$

$$S = \frac{230 \times .866 \times .26 \times .28 \times 12}{.48 \times .55^3} + \frac{230 \times .5}{.48 \times .55}$$

$$S = 2600 \text{ P.S.I.} \quad -35-$$

STRESS ANALYSIS - Continued

P E N D I N G   I N   F E E D   S L I D E   P L A T E

$$S = \frac{MC}{I} + \frac{P}{A}$$

$$S = \frac{224 \times .5 \times .094 \times 12}{75 \times .188^3} + \frac{224}{.75 \times .188}$$

$$S = 27,300 \text{ P.S.I.}$$

B E N D I N G   I N   B O T T O M   L U G S

$$S = \frac{MC}{I}$$

$$S = \frac{224 \times .5 \times .15 \times 12}{.5 \times .3^3}$$

$$S = 14,900 \text{ P.S.I.}$$

S H E A R   I N   F E E D   S L I D E   A T   P O I N T   A   (T O R S I O N)

$$S_s = \frac{T}{2ab^2} \quad (\text{FROM SPOTTS' "MACHINE DESIGN"})$$

$$S_s = \frac{.5(112)}{235 \times .31 \times .188^2}$$

$$S_s = 21,600 \text{ P.S.I.}$$

STRESS ANALYSIS - Continued

COMBINED BENDING AND SHEAR AT POINT A.

BY MOHR'S CIRCLE

$$(S_s)_{\text{MAX}} = \left( 21,600^2 + 7,450^2 \right)^{\frac{1}{2}}$$

$$S_s = 23,000 \text{ P.S.I.}$$

SHEAR STRESS FROM FEED ARM CONTACT

$$S_c = 31,90 \left( \frac{P}{D} \right)^{\frac{1}{2}}$$

$$S_c = 76,500 \text{ P.S.I.}$$

$$S_s = .304 S_c$$

$$S_s = 23,300 \text{ P.S.I.}$$

STRESS ANALYSIS - Continued

BENDING STRESS

$$\sigma = \frac{MC}{I} = \frac{4P}{\pi r^3}$$

$$S = \frac{580 \times 4 \times .15}{3.14 \times 1.5^3}$$

$$S = 57000 \text{ P.S.I.}$$

CAM FOLLOWER CONTACT STRESS

$$S_c = 5130 \left( \frac{580}{.311} \right)^{\frac{1}{2}}$$

$$S_c = 137,000 \text{ P.S.I.}$$

$$S_s = .304 S_c$$

$$S_s = 41,600 \text{ P.S.I.}$$

STRESS ANALYSIS - Continued

FEED ARM AND GEAR ANALYSIS

SHEAR STRESS IN FOLLOWER PIN

$$S = \frac{P}{A} = \frac{224}{.109}$$

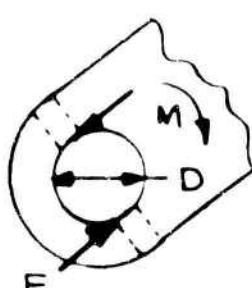
$$S = 2055 \text{ P.S.I.}$$

BEARING STRESS IN PIN HOLE

$$S = \frac{P}{A} = \frac{224}{.112}$$

$$S = 2000 \text{ P.S.I.}$$

SHEAR STRESS IN SHAFT PIN



$$M = 224 \times 2.1 = 470$$

$$F = \frac{M}{D} = \frac{470}{.5} = 940$$

$$S = \frac{P}{A} = \frac{940}{.0188}$$

$$S = 50,000 \text{ P.S.I.}$$

SHEET 5 of 9

STRESS ANALYSIS - Continued

STRESS IN GEAR KEY

SHEAR ACROSS KEY WIDTH

$$S = \frac{P}{A} = \frac{1880}{.0625}$$

$S = 30,000$  P.S.I.

CRUSHING OF KEY

$$S = \frac{P}{A} = \frac{1880}{.03175}$$

$S = 59,200$  P.S.I.

GEAR TOOTH BENDING STRESS

$$S = \frac{W P}{f Y}$$

WHERE:

$Y$  = FORM FACTOR

$W$  = DYNAMIC TOOTH LOAD

$t$  = TOOTH WIDTH

$\frac{P}{d}$  = DIAMETRAL PITCH

## STRESS ANALYSIS - Continued

$$S = \frac{553 \times 12}{.5 \times 322}$$

$$S = 41,100 \text{ P.S.I.}$$

SINCE, FOR MATING GEAR IS LARGER  
THE STRESS WILL BE LOWER

SHEAR STRESS IN FEED GEAR PIN

$$M = 1.125 \times 553 = 622$$

$$F = \frac{622}{.6} = 1036$$

$$S = \frac{F}{A} = \frac{1036}{.027}$$

$$S = 38,400 \text{ P.S.I.}$$

STRESS IN FOLLOWER ARMSHEAR STRESS

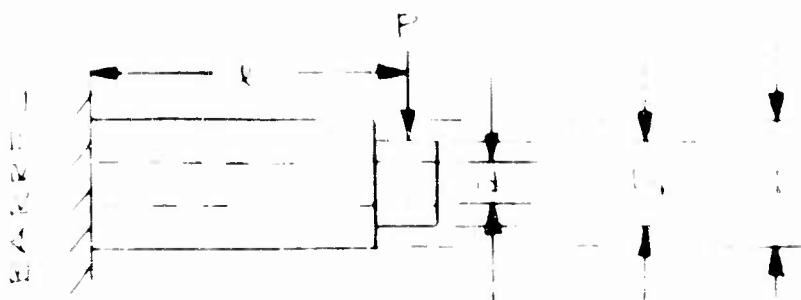
$$S = \frac{P}{A}$$

$$S = \frac{580}{.07}$$

$$S = 8,300 \text{ P.S.I.}$$

STRESS ANALYSIS - Continued

STRESS IN FOLLOWING AREA (BARREL)



$$P = 160 \text{ kip}$$

$$L = 1$$

$$D_f = 6.25$$

$$D_o = 4.16$$

SHEAR AT SHOULDER

$$S = \frac{F}{A}$$

$$S = \frac{P \cdot L}{\pi(D_f^2 - D_o^2)}$$

$$S = 1,350 \text{ P.S.I.}$$

BENDING AT BARREL

$$S = \frac{M}{Z} = \frac{4 M R}{\pi(R^4 - r^4)}$$

$$S = 4,400 \text{ P.S.I.}$$

STRESS ANALYSIS - Continued

BEARING STRESS ON BARREL CAM

FOLLOWER DURING FIRING

TORQUE = 705 IN #

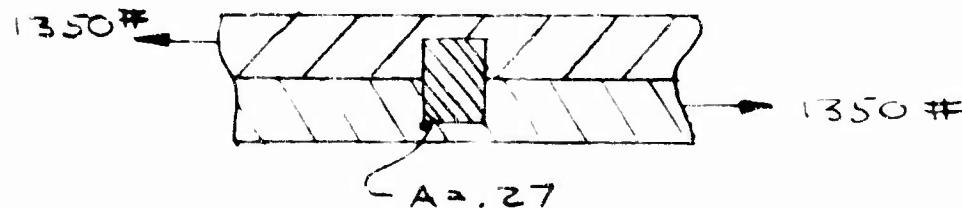
$$F = \frac{T}{R} = \frac{705}{1.2} = 590 \text{ #}$$

$$S = \frac{F}{D}$$

$$S = \frac{590}{.25}$$

$$S = 2,360 \text{ P.S.I.}$$

SHARP STRESS IN BARREL LOCK



$$S = \frac{F}{A}$$

$$S = \frac{1350}{.27}$$

$$S = 5000 \text{ P.S.I.}$$